



Heat and Mass Transfer Institute

Smart Polishing Technology

Magnetorheological finishing (MRF) is a deterministic method for producing complex optics with figure accuracy < 50 nm and surface roughness < 1 nm



Outline

- **History. Introduction.**
- **Advantages of magnetorheological polishing**
- **Application, HMTI expertise**
- **General aim of R&D project**

History

- 1987 – A magnetorheological fluid was used for the first time in joint work of the Heat and Mass Transfer Institute with the Institute of Optical machine –Tool Manufacture.**
- 1988 - A prototype machine for magnetorheological finishing was awarded a silver medal of the All- Union Exhibition of the Achievements of the National Economy of USSR.**

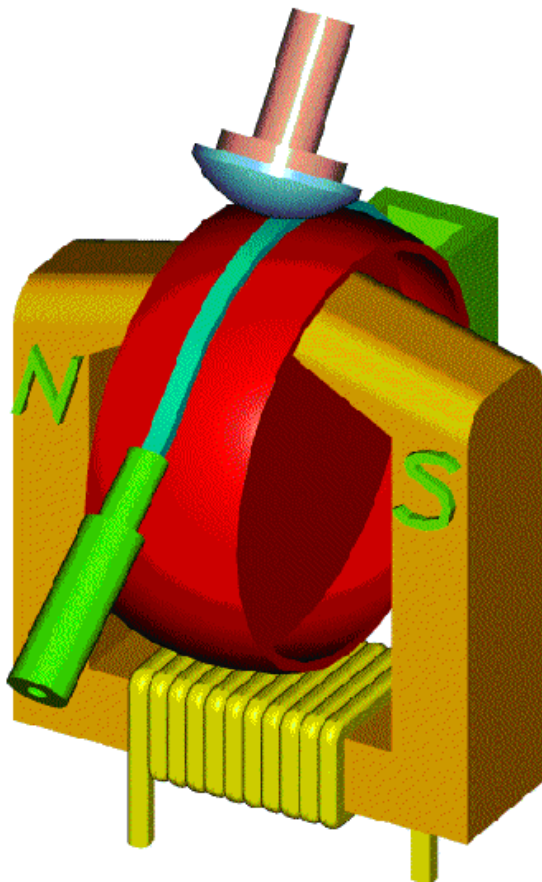


- 1990 - Some HMTI researchers moved from USSR to USA and established QED company that focused in magnetorheological finishing**





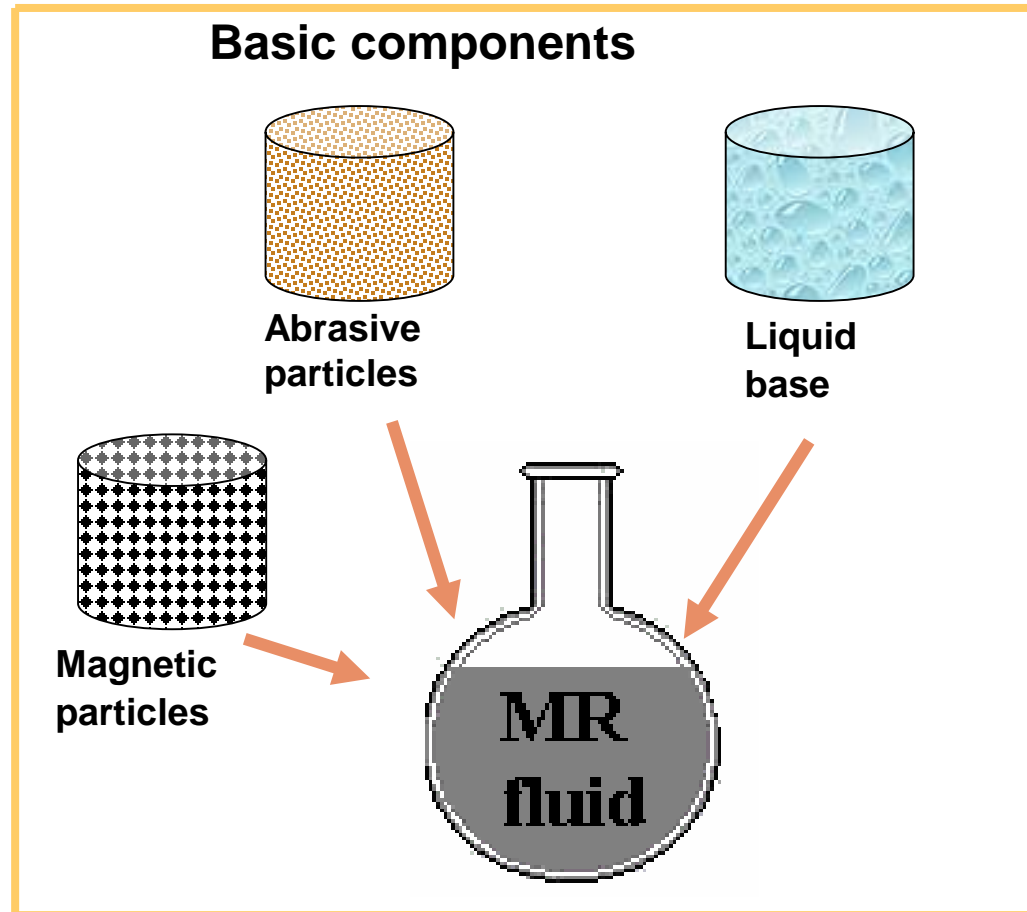
Introduction



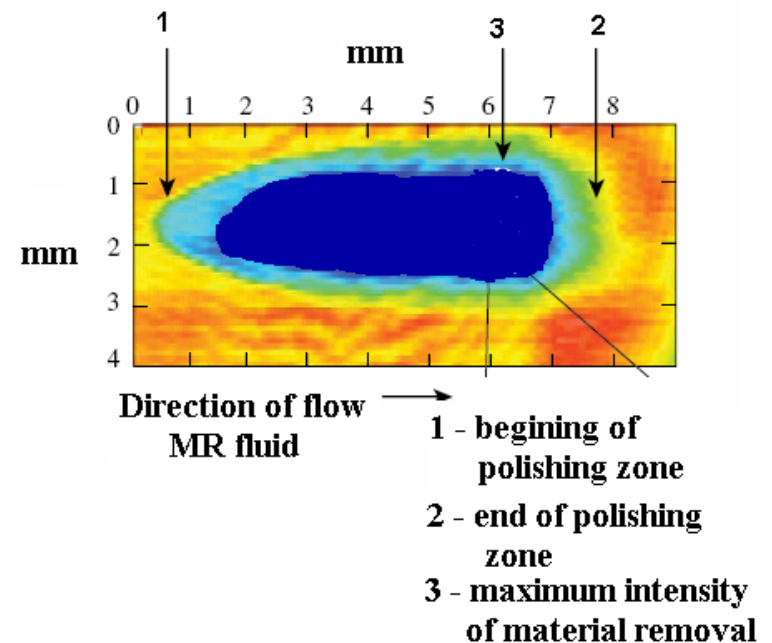
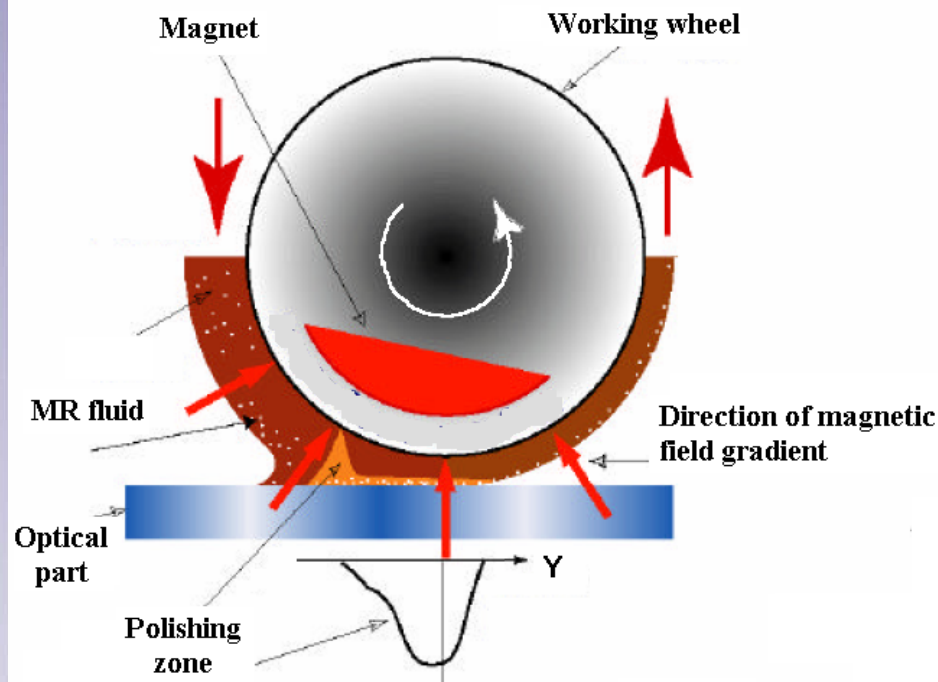
The technology of magnetorheological finishing (MRF) – a high-quality technique of processing optical and semiconductor parts. It is based on the alteration of the rheological properties of a magnetorheological polishing fluid (MR fluid) on exposure to a magnetic field. In a magnetic field an MR fluid becomes a viscoelastic medium acting as a polishing material.



Magnetorheological Fluid



MRF Technology



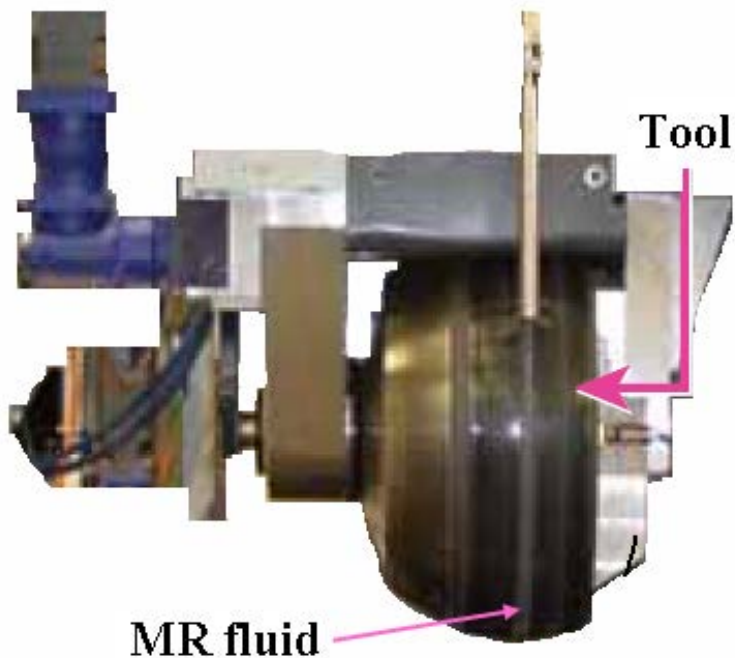
Formation of polishing zone after the contact of MR fluid with the surface of the part on exposure to gradient magnetic field

MRF Equipment

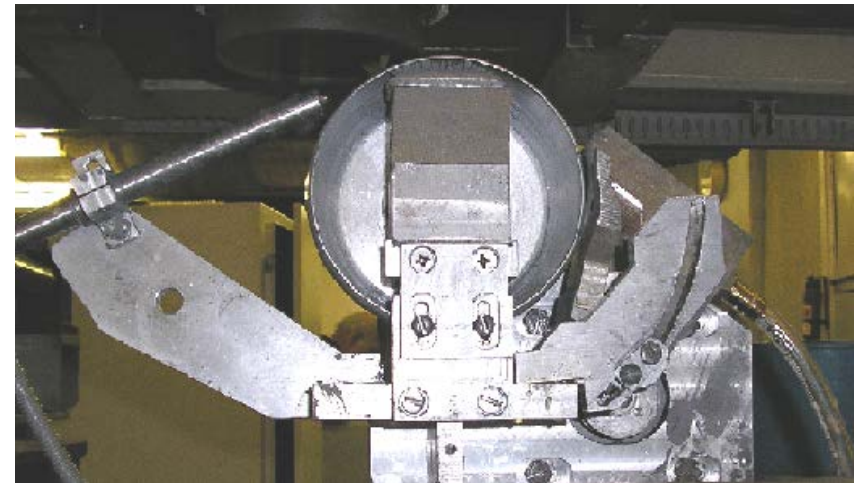


MRF polishing machines produced at Heat and Mass Transfer Institute

MR Polishing Module



MR working tool with its position
above the part processed



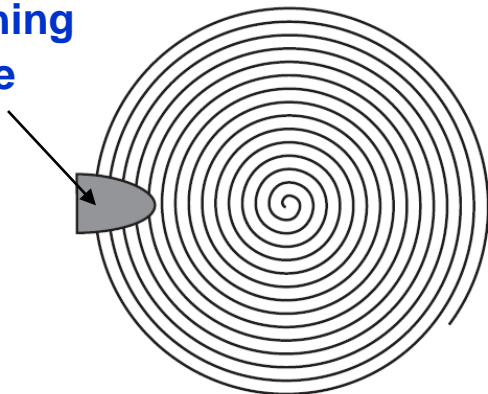
MR working tool configuration with its
position above the part to be polished
below



Software

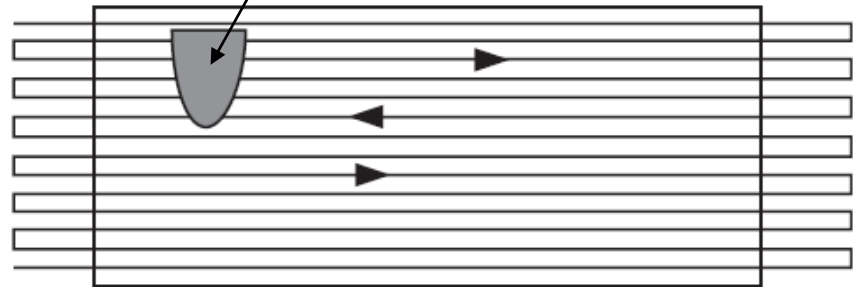
- Program monitoring the shaping of the part
- Software controlling part motion
- Program controlling MR fluid stability
- Simulation regimes of MR polishing

Polishing
zone



Spiral trajectory in the case
axysymmetrical rotation of the part

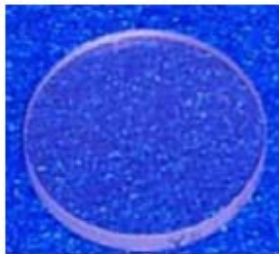
Polishing
zone



Raster trajectory. The part does
not rotate

Diagnostics

BaF₂



Rq- 0,9 nm

Optical glass K8



Rq- 0,6 nm

**Polycrystalline
ZnS**



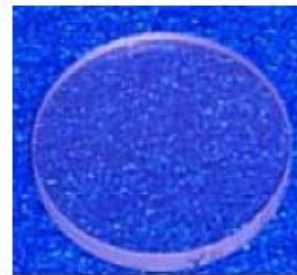
Rq - 0,8 nm

Sitall



Rq - 0,22 nm

LiF



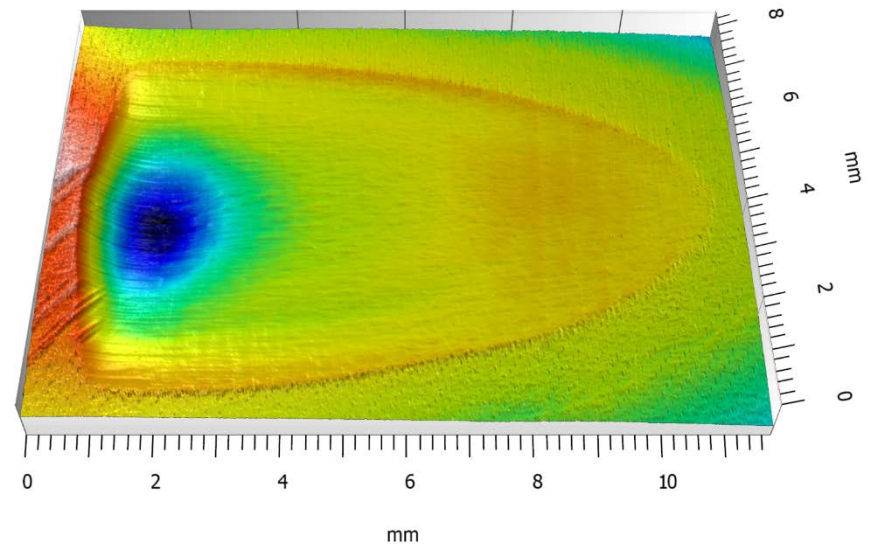
Rq - 1,2 nm

Examples of the surface quality control by AFM

3D Optical Profiler Diagnostic



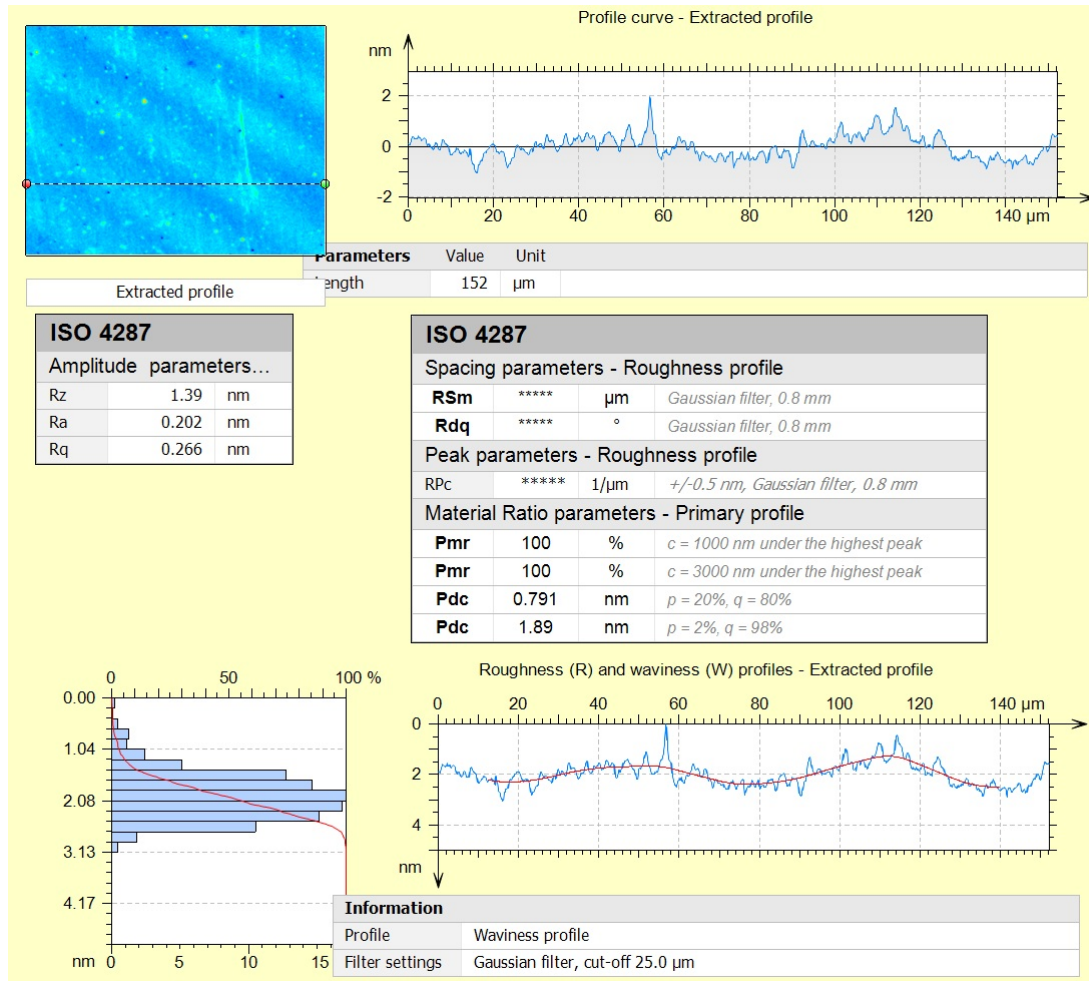
**3D Optical Profiler MicroXAM-800
(KLA-Tencor, USA)**



3D view of polishing zone



Complex analysis of Roughness and Waviness parameters



Surface of laser component
from Beta-Barium Borate
(β -BaB₂O₄ or BBO) after
magnetorheological polishing
Ra = 0,202 nm

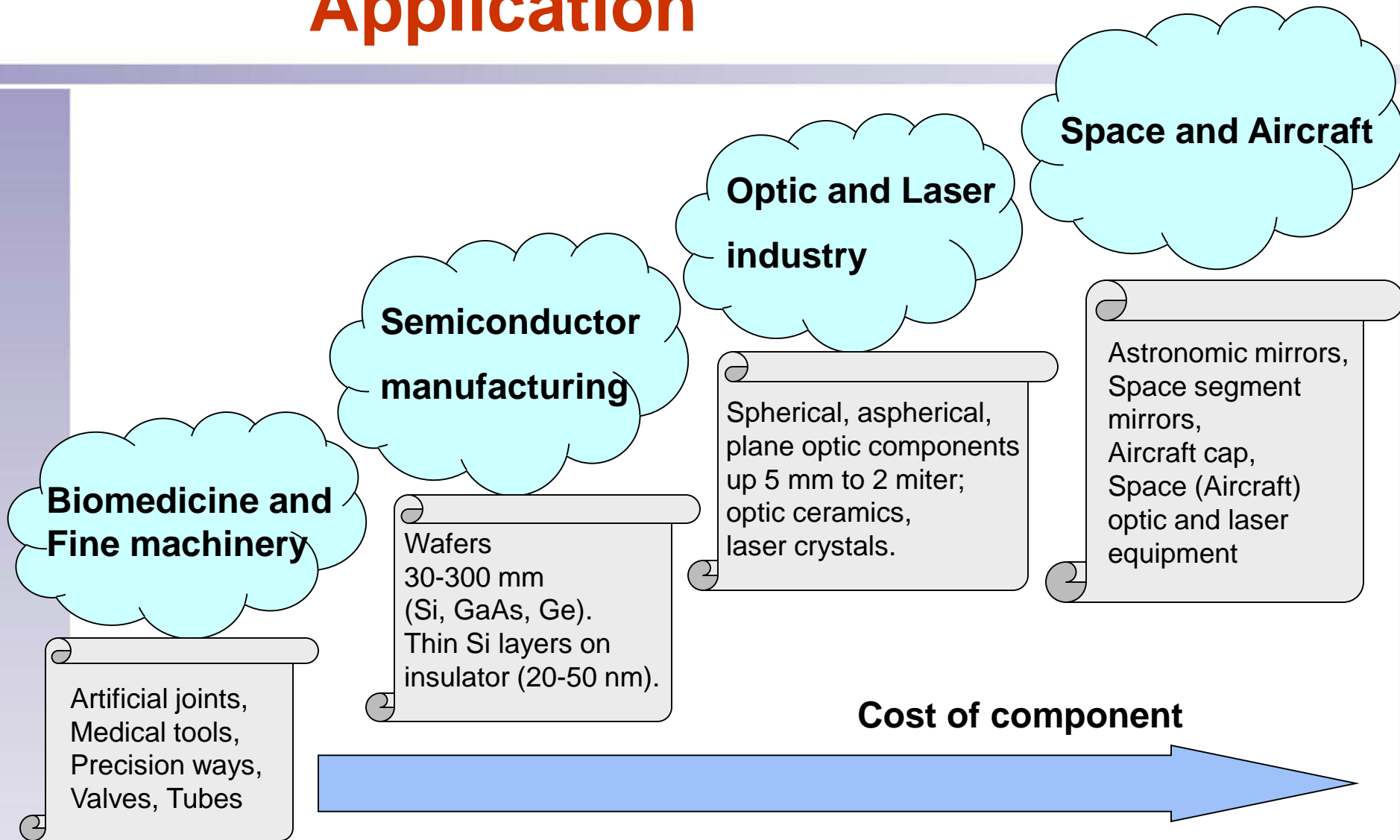


Advantages of MRF technology

1. Shape of the surface of the parts processed: spherical (convex, concave); aspherical (convex, concave); plane
2. Size of the parts from 3 mm to 2 meter (and more)
3. Error in the shape of the surface typically $\lambda/100$ and lower
4. Process with high level of automation with predictable quality
5. Wide range of materials, including super hard ceramics, non-magnetic metals and composites.
6. Open market to Russia, China, India, Brazil and etc.

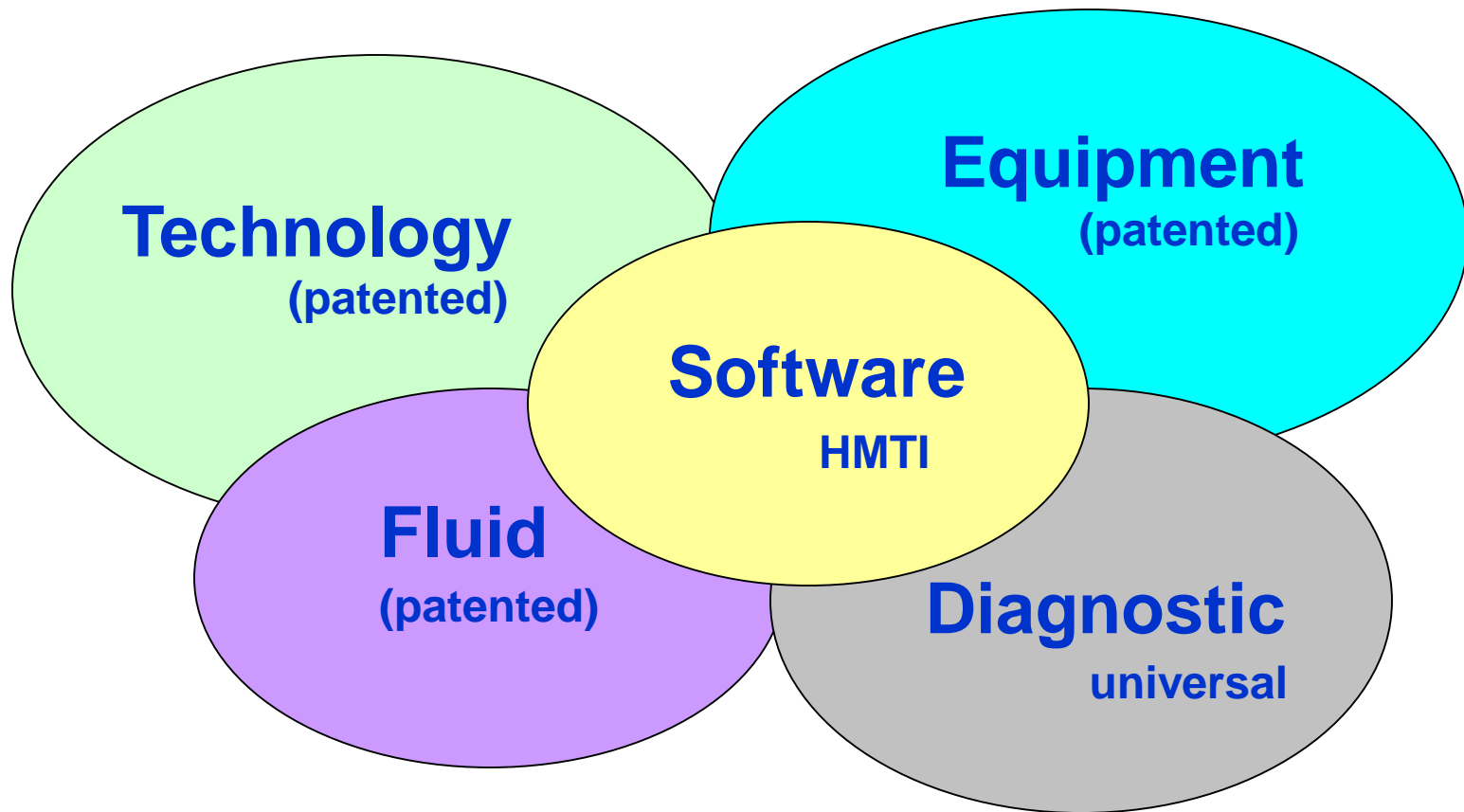


Application





HMTI expertise in MRF



General aim of R&D project

V



I



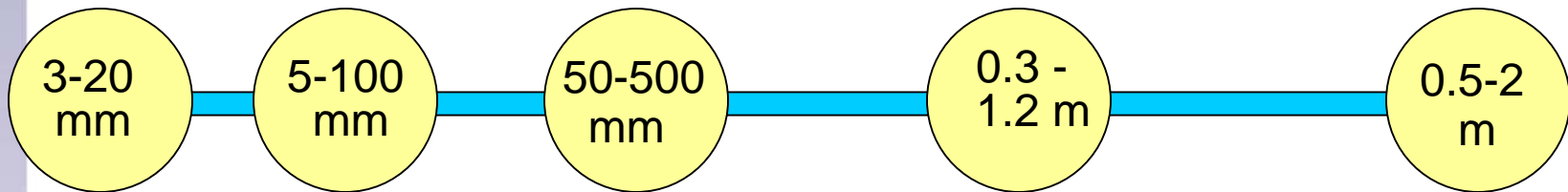
II



III



IV



Dimension of treated component

General aim of the project is to create **Series of MRF machines (5 machines)** for covering large share of market of modern and unique components production with part dimensions up 3 mm to 2m



Thank you for attention!